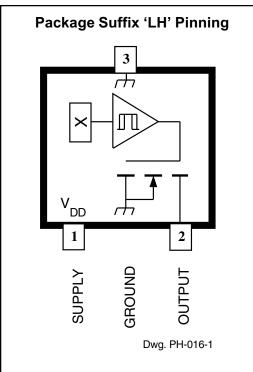
# 3209 AND 3210

# MICROPOWER, ULTRA-SENSITIVE HALL-EFFECT SWITCHES



Pinning is shown viewed from branded side.

#### ABSOLUTE MAXIMUM RATINGS at $T_A = +25^{\circ}C$

Supply Voltage, $V_{DD}$ 5 V
Magnetic Flux Density, B Unlimited
Output Off Voltage, $V_{OUT}$ 5 V
Output Current, I <sub>OUT</sub> 1 mA
Junction Temperature, $T_J$ +170°C
Operating Temperature Range, $T_A$ 40°C to +85°C
Storage Temperature Range, T <sub>S</sub> 65°C to +170°C
Caution: These CMOS devices have input static protection (Class 3) but are still

static protection (Class 3) but are still susceptible to damage if exposed to extremely high static electrical charges. The A3209Ex and A3210Ex integrated circuits are ultra-sensitive, pole independent Hall-effect switches with a latched digital output. They are especially suited for operation in battery-operated, hand-held equipment such as cellular and cordless telephones, pagers, and palmtop computers. 2.5 volt to 3.5 volt operation and a unique clocking scheme to reduce the average operating power requirements – the A3209Ex to 400  $\mu$ W, the A3210Ex to 25  $\mu$ W! Except for operating duty cycle and average operating current, the A3209Ex and A3210Ex are identical.

Unlike other Hall-effect switches, either a north <u>or</u> south pole of sufficient strength will turn the output on; in the absence of a magnetic field, the output is off. The polarity independence and minimal power requirement allows these devices to easily replace reed switches for superior reliability and ease of manufacturing, while eliminating the requirement for signal conditioning.

Improved stability is made possible through chopper stabilization (dynamic offset cancellation), which reduces the residual offset voltage normally caused by device overmolding, temperature dependencies, and thermal stress.

These devices include on a single silicon chip a Hall-voltage generator, small-signal amplifier, chopper stabilization, a latch, and a MOSFET output. Advanced BiCMOS processing is used to take advantage of low-voltage and low-power requirements, component matching, very low input-offset errors, and small component geometries.

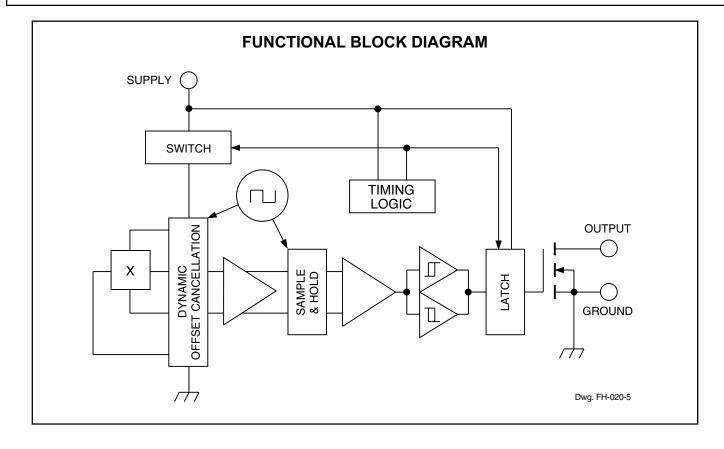
The A3209Ex and A3210Ex are rated for operation over a temperature range of -40°C to +85°C. Two package styles provide a magnetically optimized package for most applications. Suffix 'LH' is a miniature low-profile surface-mount package while suffix 'UA' is a three-lead ultra-mini-SIP for through-hole or surface mounting.

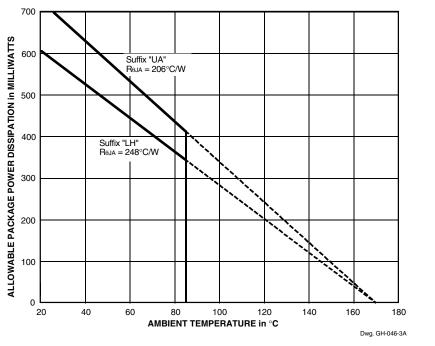
#### FEATURES

- Micropower Operation
- Operate With North or South Pole
- 2.5 V to 3.5 V Battery Operation
- Chopper Stabilized Superior Temperature Stability Extremely Low Switch-Point Drift Insensitive to Physical Stress
- ESD Protected to 5 kV
- Solid-State Reliability
- Small Size
- Easily Manufacturable With Magnet Pole Independence

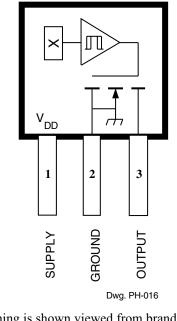
Always order by complete part number: the prefix 'A' + the basic four-digit part number + the suffix 'E' to indicate operating temperature range + a suffix to indicate package style, e.g., **A3210ELH**.

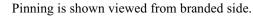






Package Suffix 'UA' Pinning







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#### ELECTRICAL CHARACTERISTICS with C<sub>BYPASS</sub> = 0.1 $\mu$ F, over operating voltage and temperature range (unless otherwise specified).

				Limits			
Characteristic	Symbol	Test Conditions	Min.	Тур.	Max.	Units	
Supply Voltage Range	V <sub>DD</sub>	Operating <sup>1)</sup>	2.5	2.75	3.5	V	
Output Leakage Current	I <sub>OFF</sub>	V <sub>OUT</sub> = 3.5 V, B <sub>RPN</sub> < B < B <sub>RPS</sub>	-	«1.0	1.0	μA	
Output On Voltage	V <sub>OUT</sub>	I <sub>OUT</sub> = 1 mA, V <sub>DD</sub> = 2.5 V	-	105	300	mV	
Awake Time	t <sub>awake</sub>		30	60	90	μs	
Period	t <sub>period</sub>	A3209Ex	240	480	720	μs	
		A3210Ex	30	60	90	ms	
Duty Cycle	d.c.	A3209Ex	-	12.5	_	%	
		A3210Ex	-	0.10	_	%	
Chopping Frequency	f <sub>C</sub>		-	340	_	kHz	
Supply Current	I <sub>DD(EN)</sub>	Chip awake (enabled)	0.1	_	3.0	mA	
$(2.5 \leq V_{DD} \leq 3.5 \text{ V})$	I <sub>DD(DIS)</sub>	Chip asleep (disabled)	1.0	10	50	μA	
	I <sub>DD(AVG)</sub>	A3209Ex, V <sub>DD</sub> = 2.75 V	-	145	425	μA	
		A3209Ex, V <sub>DD</sub> = 3.5 V	-	195	425	μA	
		A3210Ex, V <sub>DD</sub> = 2.75 V	-	8.8	25	μA	
		A3210Ex, V <sub>DD</sub> = 3.5 V	-	13	60	μA	

NOTES: 1. Operate and release points will vary with supply voltage.

2.  $B_{OPx}$  = operate point (output turns ON);  $B_{RPx}$  = release point (output turns OFF). 3. Typical Data is at  $T_A$  = +25°C and  $V_{DD}$  = 2.75 V and is for design information only.

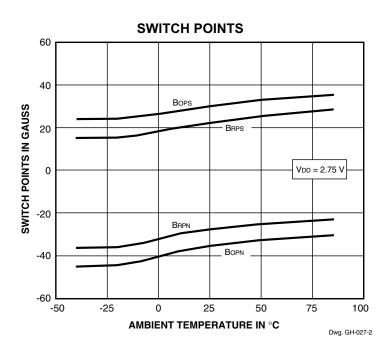
#### MAGNETIC CHARACTERISTICS with $C_{BYPASS} = 0.1 \ \mu F$ , over operating voltage and temperature range (unless otherwise specified).

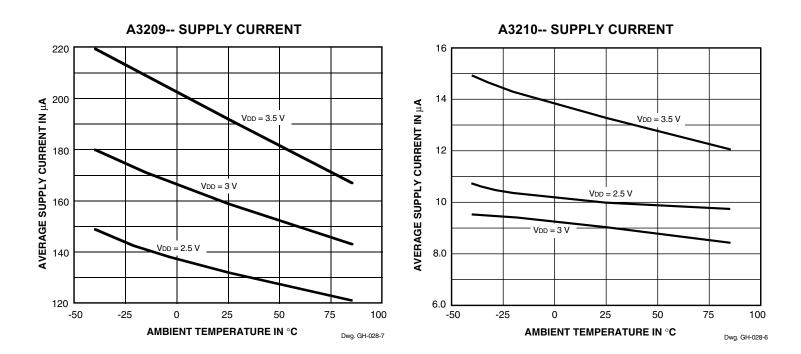
			Limits			
Characteristic	Symbol	Test Conditions	Min.	Тур.	Max.	Units
Operate Points	B <sub>OPS</sub>	B <sub>OPS</sub> South pole to branded side		30	60	G
	B <sub>OPN</sub>	North pole to branded side	-60	-35	_	G
Release Points	B <sub>RPS</sub>	South pole to branded side	5.0	22	_	G
	B <sub>RPN</sub>	North pole to branded side	-	-27	-5.0	G
Hysteresis	B <sub>hys</sub>	B <sub>OPx</sub> - B <sub>RPx</sub>	_	7.7	_	G

NOTES: 1. As used here, negative flux densities are defined as less than zero (algebraic convention) and -50 G is less than +10 G.

2. Typical Data is at  $T_A = +25^{\circ}C$  and  $V_{DD} = 2.75$  V and is for design information only.

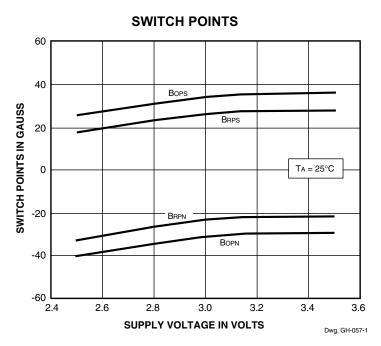
#### TYPICAL OPERATING CHARACTERISTICS as a function of temperature





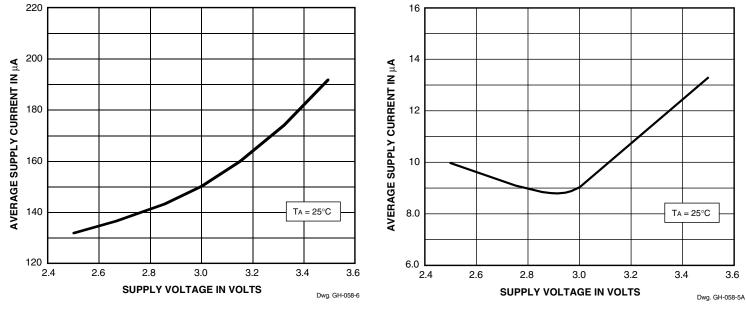


#### TYPICAL OPERATING CHARACTERISTICS as a function of supply voltage



A3209-- SUPPLY CURRENT

A3210-- SUPPLY CURRENT



## **CRITERIA FOR DEVICE QUALIFICATION**

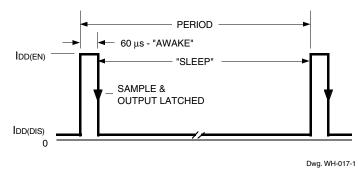
All Allegro sensors are subjected to stringent qualification requirements prior to being released to production. To become qualified, except for the destructive ESD tests, no failures are permitted.

Qualification Test	Test Method and Test Conditions	Test Length	Samples	Comments
Biased Humidity (HAST)	T <sub>A</sub> = 130°C, RH = 85%	50 hrs	77	$V_{DD} = V_{OUT} = 3 V$
High-Temperature Operating Life (HTOL)	JESD22-A108, T <sub>A</sub> = 150°C, T <sub>J</sub> ≤ 165°C	408 hrs	77	$V_{DD} = V_{OUT} = 3 V$
Accelerated HTOL	$T_{A} = 175^{\circ}C, T_{J} \le 190^{\circ}C$	504 hrs	77	$V_{DD} = V_{OUT} = 3 V$
Autoclave, Unbiased	JESD22-A102, Condition C, T <sub>A</sub> = 121°C, 15 psig	96 hrs	77	
High-Temperature (Bake) Storage Life	MIL-STD-883, Method 1008, T <sub>A</sub> = 170°C	1000 hrs	77	
Temperature Cycle	MIL-STD-883, Method 1010, -65°C to +150°C	500 cycles	77	
Latch-Up	_	Pre/Post Reading	6	
Electro-Thermally Induced Gate Leakage	_	Pre/Post Reading	6	
ESD, Human Body Model	CDF-AEC-Q100-002	Pre/Post Reading	3 per test	Test to failure, All leads > 5 kV
ESD, Machine Model	JESD22-A115	Pre/Post Reading	3 per test	Test to failure, All leads > 350 V
Electrical Distributions	Per Specification	_	30	



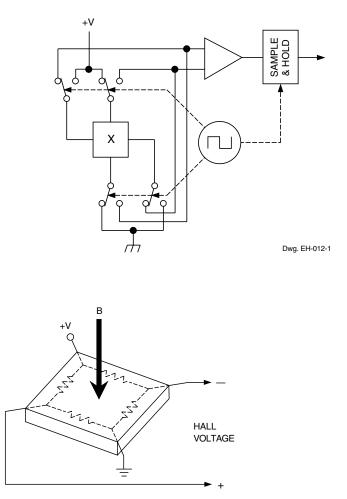
## FUNCTIONAL DESCRIPTION

**Low Average Power.** Internal timing circuitry activates the sensor for 60  $\mu$ s and deactivates it for the remainder of the period (480  $\mu$ s for the A3209Ex and 60 ms for the A3210Ex). A short "awake" time allows for stabilization prior to the sensor sampling and data latching on the falling edge of the timing pulse. The output during the "sleep" time is latched in the last sampled state. The supply current is not affected by the output state.



Chopper-Stabilized Technique. The Hall element can be considered as a resistor array similar to a Wheatstone bridge. A large portion of the offset is a result of the mismatching of these resistors. These devices use a proprietary dynamic offset cancellation technique, with an internal high-frequency clock to reduce the residual offset voltage of the Hall element that is normally caused by device overmolding, temperature dependencies, and thermal stress. The chopper-stabilizing technique cancels the mismatching of the resistor circuit by changing the direction of the current flowing through the Hall plate using CMOS switches and Hall voltage measurement taps, while maintaing the Hall-voltage signal that is induced by the external magnetic flux. The signal is then captured by a sample-andhold circuit and further processed using low-offset bipolar circuitry. This technique produces devices that have an extremely stable quiescent Hall output voltage, are immune to thermal stress, and have precise recoverability after temperature cycling. This technique will also slightly degrade the device output repeatability. A relatively high sampling frequency is used in order that faster signals can be processed.

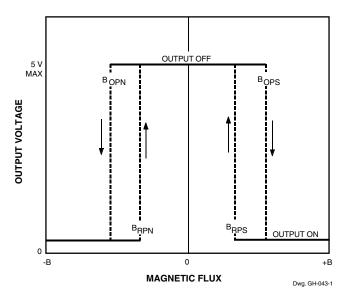
More detailed descriptions of the circuit operation can be found in: Technical Paper STP 97-10, *Monolithic Magnetic Hall Sensor Using Dynamic Quadrature Offset Cancellation* and Technical Paper STP 99-1, *Chopper-Stabilized Amplifiers With A Track-and-Hold Signal Demodulator*.



Dwg. AH-011-2

**Operation.** The output of this device switches low (turns on) when a magnetic field perpendicular to the Hall sensor exceeds the operate point  $B_{OPS}$  (or is less than  $B_{OPN}$ ). After turn-on, the output is capable of sinking up to 1 mA and the output voltage is  $V_{OUT(ON)}$ . When the magnetic field is reduced below the release point  $B_{RPS}$  (or increased above  $B_{RPN}$ ), the device output switches high (turns off). The difference in the magnetic operate and release points is the hysteresis ( $B_{hys}$ ) of the device. This built-in hysteresis allows clean switching of the output even in the presence of external mechanical vibration and electrical noise.

As used here, negative flux densities are defined as less than zero (algebraic convention) and -50 G is less than +10 G.

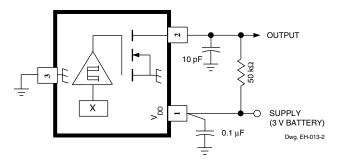


**Applications.** Allegro's pole-independent sensing technique allows for operation with either a north pole or south pole magnet orientation, enhancing the manufacturability of the device. The state-of-the-art technology provides the same output polarity for either pole face.

It is strongly recommended that an external bypass capacitor be connected (in close proximity to the Hall sensor) between the supply and ground of the device to reduce both external noise and noise generated by the chopper-stabilization technique. This is especially true due to the relatively high impedance of battery supplies.

The simplest form of magnet that will operate these devices is a bar magnet with either pole near the branded surface of the device. Many other methods of operation are possible. Extensive applications information on magnets and Hall-effect sensors is also available in the *Allegro Electronic Data Book* AMS-702 or *Application Note* 27701, or at

#### www.allegromicro.com

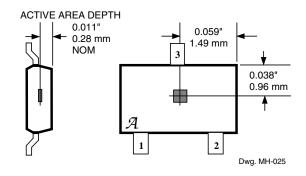


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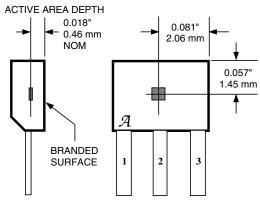
8

#### SENSOR LOCATIONS (±0.005" [0.13 mm] die placement)





#### Package Designators 'UA', UA-LC', and 'UA-TL'

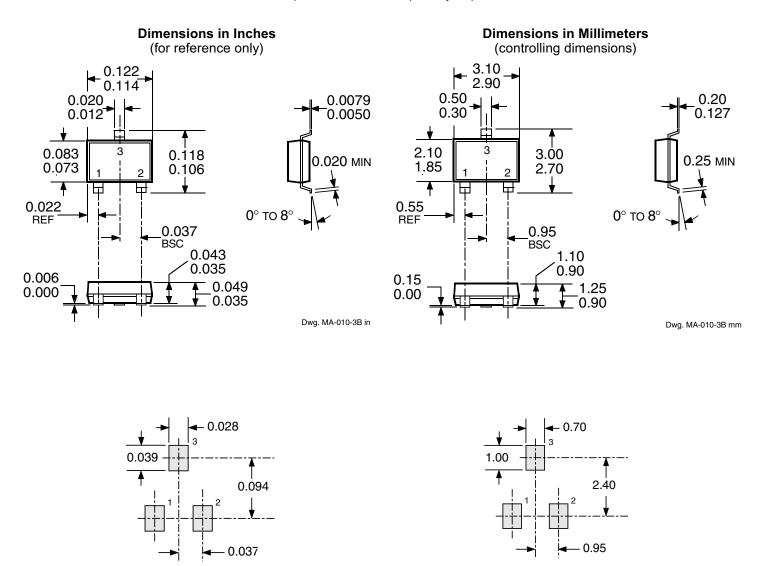


Dwg. MH-011-11

Although sensor location is accurate to three sigma for a particular design, product improvements may result in small changes to sensor location.

#### PACKAGE DESIGNATOR 'LH'

(fits SC-74A solder-pad layout)



Dwg. MA-011-3 in

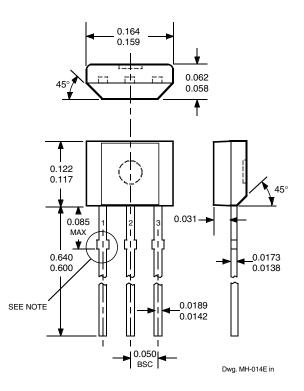


NOTES: 1. Tolerances on package height and width represent allowable mold offsets. Dimensions given are measured at the widest point (parting line).

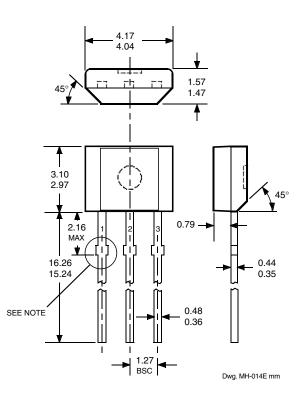
- 2. Exact body and lead configuration at vendor's option within limits shown.
- 3. Height does not include mold gate flash.
- 4. Where no tolerance is specified, dimension is nominal.

#### **PACKAGE DESIGNATOR 'UA'**

**Dimensions in Inches** (controlling dimensions)



Dimensions in Millimeters (for reference only)

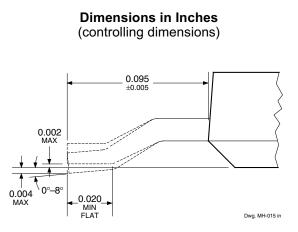


NOTES: 1. Tolerances on package height and width represent allowable mold offsets. Dimensions given are measured at the widest point (parting line).

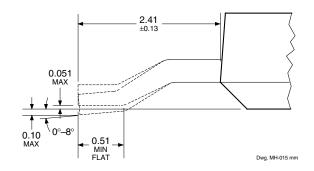
- 2. Exact body and lead configuration at vendor's option within limits shown.
- 3. Height does not include mold gate flash.
- 4. Recommended minimum PWB hole diameter to clear transition area is 0.035" (0.89 mm).
- 5. Where no tolerance is specified, dimension is nominal.



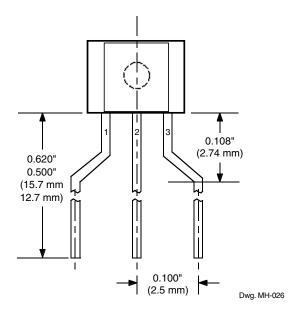
### Surface-Mount Lead Form (order A32xxEUA-TL)



#### Dimensions in Millimeters (for reference only)



#### Radial Lead Form (order A32xxEUA-LC)



NOTE: Lead-form dimensions are the nominals produced on the forming equipment. No dimensional tolerance is implied or guaranteed for bulk packaging (500 pieces per bag).

The products described herein are manufactured under one or more of the following U.S. patents: 5,045,920; 5,264,783; 5,442,283; 5,389,889; 5,581,179; 5,517,112; 5,619,137; 5,621,319; 5,650,719; 5,686,894; 5,694,038; 5,729,130; 5,917,320; and other patents pending.

Allegro MicroSystems, Inc. reserves the right to make, from time to time, such departures from the detail specifications as may be required to permit improvements in the performance, reliability, or manufacturability of its products. Before placing an order, the user is cautioned to verify that the information being relied upon is current.

Allegro products are not authorized for use as critical components in life-support appliances, devices, or systems without express written approval.

The information included herein is believed to be accurate and reliable. However, Allegro MicroSystems, Inc. assumes no responsibility for its use; nor for any infringements of patents or other rights of third parties that may result from its use.

# HALL-EFFECT SENSORS

Partial Part	Avail. Ope	r. Charao	cteristics at <sup>-</sup>	T <sub>A</sub> = +25°C		
Number	Temp.	BOP max	B <sub>RP</sub> min	B <sub>hys</sub> typ	Features	Notes
	HALL-EFFE		R & OMNIPO	LAR SWITCH	ES in order of B <sub>OP</sub> and B <sub>hys</sub>	
3240	E/L	+50	+5.0	10	chopper stabilized	1
3209	E	±60	±5.0	7.7	400 µW, chopper stabilized	
3210	E E E	±60	±5.0	7.7	25 $\mu$ W, chopper stabilized	
3361	E	+125	+40	5.0*	2-wire, chopper stabilized, inverte	ed output
3362	E	+125	+40	5.0*	2-wire, chopper stabilized	
3161	E	+160	+30	20	2-wire	
3141	E/L	+160	+10	55		
3235	S	+175	+25	15*	output 1	2 2 1
		-25	-175	15*	output 2	2
5140	E	+200	+50	55	300 mA power driver output	1
3142	E/L	+230	+75	55		
3143	E/L	+340	+165	55		
3144	E/L	+350	+50	55		
3122	E/L	+400	+140	105		
3123	E/L	+440	+180	105		
3121	E/L	+450	+125	105		
	HALL-EFF	ECT LATCHE	S & BIPOLA	R SWITCHES	<sup>†</sup> in order of BOP and B <sub>hys</sub>	
3260	E/L	+30	-30	20	bipolar switch, chopper stabilized	1
3280	E/L	+40	-40	45	chopper stabilized	
3134	E/L	+50	-50	27	bipolar switch	
3133	K/L/S	+75	-75	52	bipolar switch	
3281	E/L	+90	-90	100	chopper stabilized	
3132	K/L/S	+95	-95	52	bipolar switch	
3187	E/L	+150	-150	100*		
3177	S	+150	-150	200		
3625	S	+150	-150	200	900 mA power driver output	1, 3
3626	S	+150	-150	200	400 mA power driver output	1, 3
3195	E/L	+160	-160	220	active pulldown	1
3197	L	+160	-160	230		1
3175	S	+170	-170	200		
3188	E/L	+180	-180	200*		
3283	E/L	+180	-180	300	chopper stabilized	
3189	E/L	+230	-230	100*	••	
3275	S	+250	-250	100*		3
	E/L	+270	-270	340*		

Operating Temperature Ranges:

 $S = -20^{\circ}C$  to  $+85^{\circ}C$ ,  $E = -40^{\circ}C$  to  $+85^{\circ}C$ ,  $J = -40^{\circ}C$  to  $+115^{\circ}C$ ,  $K = -40^{\circ}C$  to  $+125^{\circ}C$ ,  $L = -40^{\circ}C$  to  $+150^{\circ}C$ 

Notes 1. Protected.

2. Output 1 switches on south pole, output 2 switches on north pole for 2-phase, bifilar-wound, unipolar-driven brushless dc motor control. Outputs may be tied together for omnipolar operation.

3. Complementary outputs for 2-phase bifilar-wound, unipolar-driven brushless dc motor control.

\* Minimum. ‡ Maximum

<sup>†</sup> Latches will <u>not</u> switch on removal of magnetic field; bipolar switches <u>may</u> switch on removal of field but require field reversal for reliable operation over operating temperature range.

